Reasoning with Inconsistency

Mike Giancola
Selmer Bringsjord

RAIR
Rensselaer AI and Reasoning Lab

Intermediate Formal Logic & AI (IFLAI-2)
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Sponsored by

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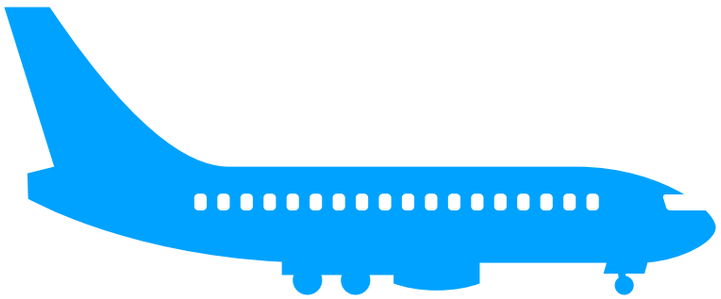
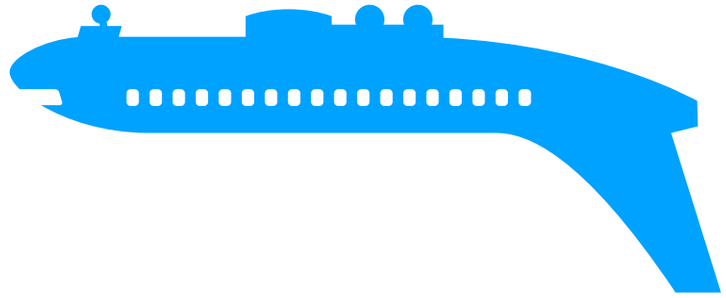
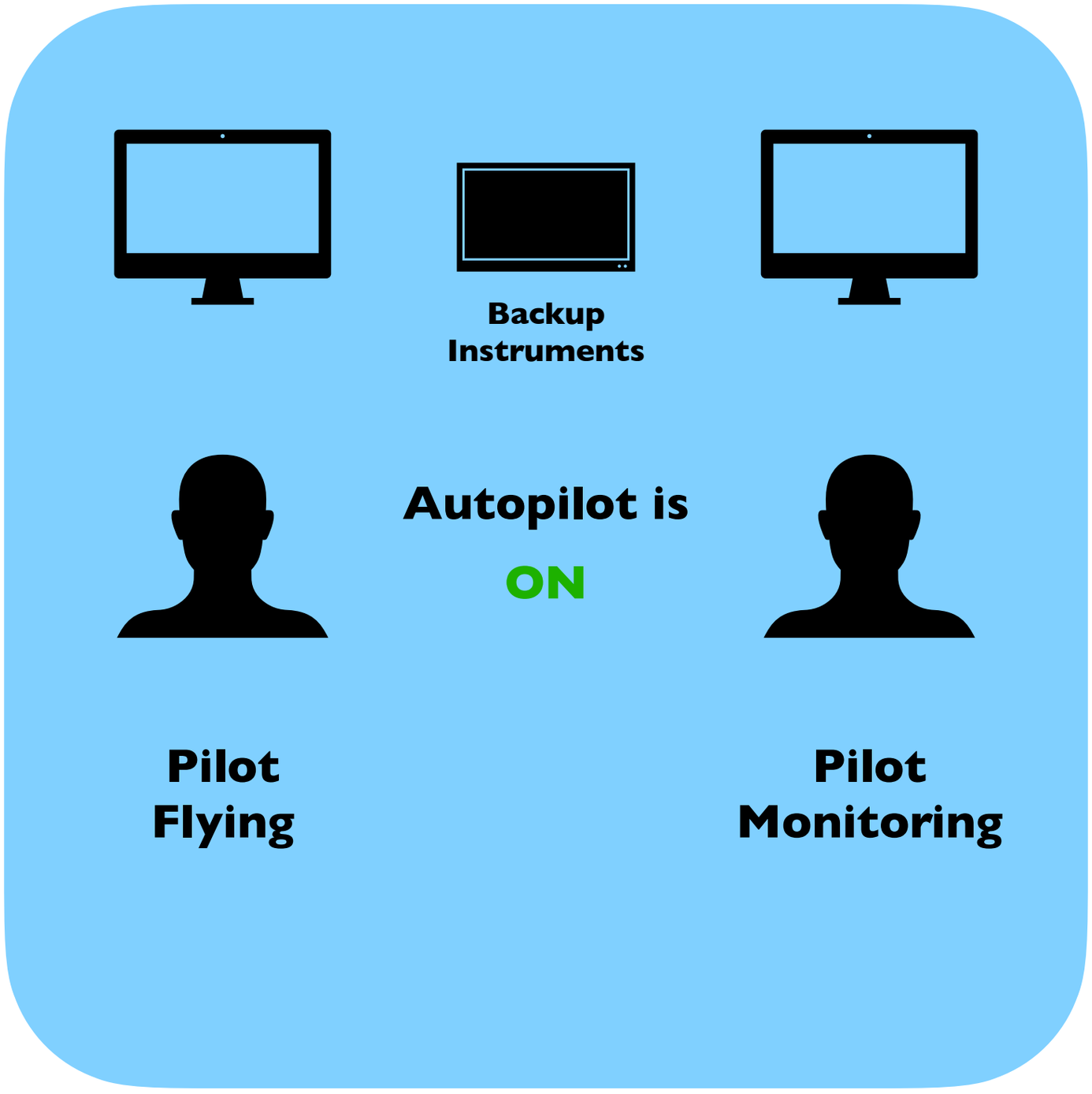
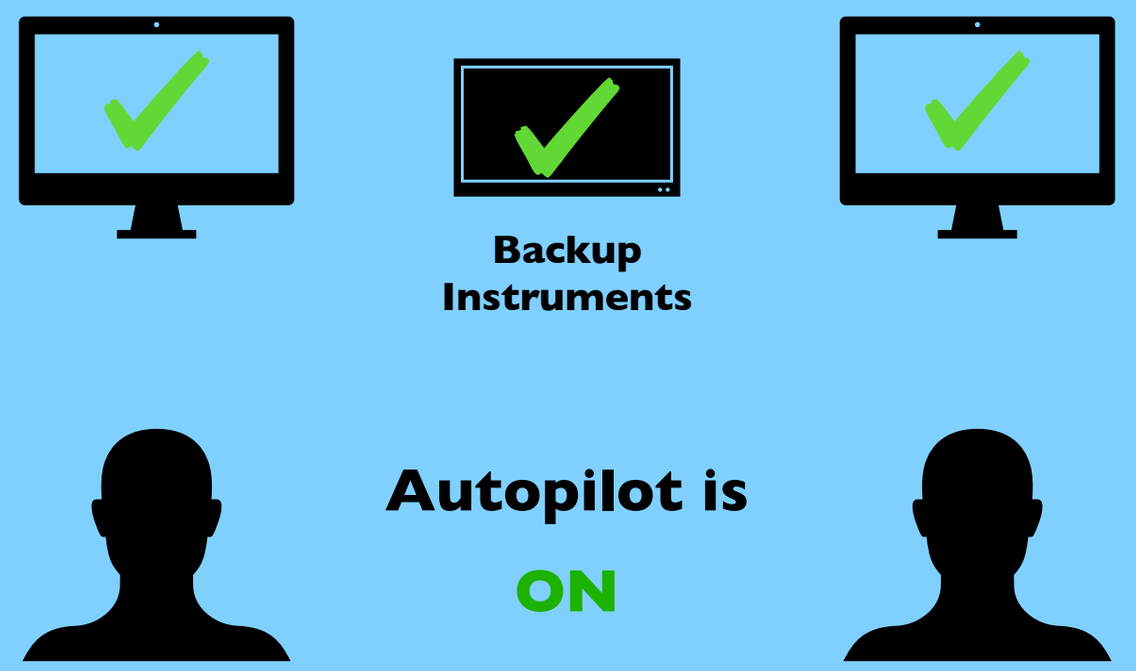
Hard!

- **Goal:** Build an AI agent which can detect inconsistencies and find solutions






Backup
Instruments
Autopilot is
ON
Pilot
Flying
Pilot
Monitoring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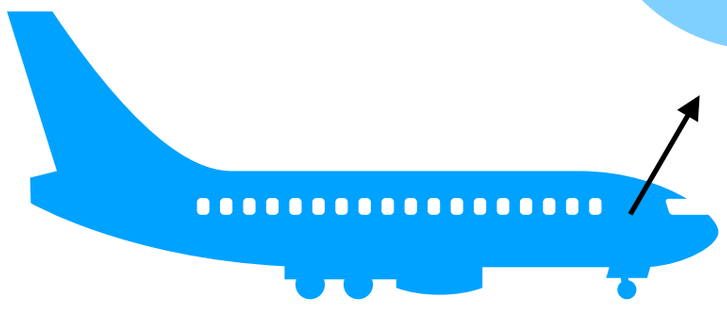
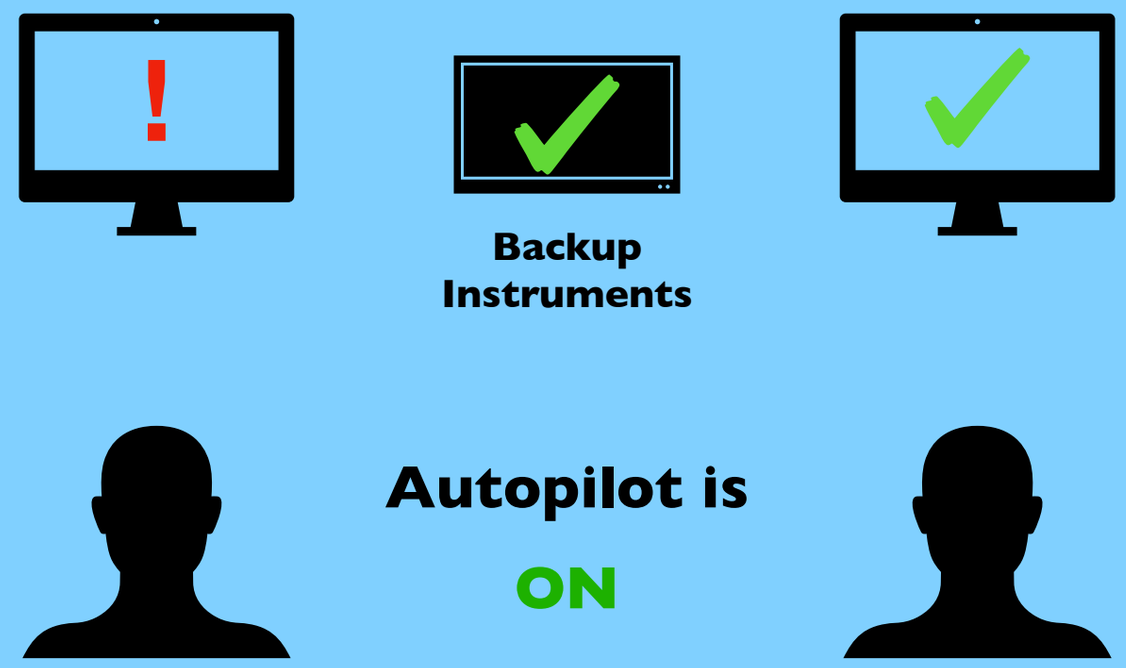
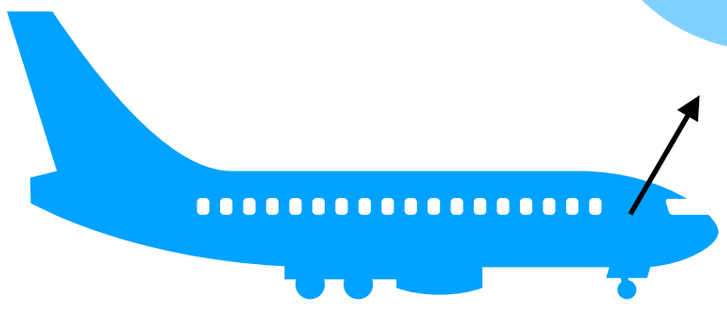


Time:

t0

Pitch is too high!



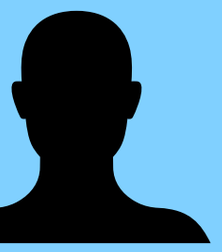


Time:

t_1

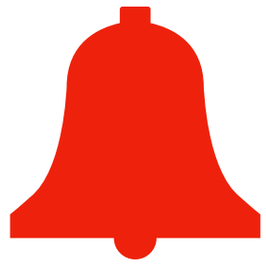
Pitch is too high!

Backup Instruments



Autopilot is

OFF

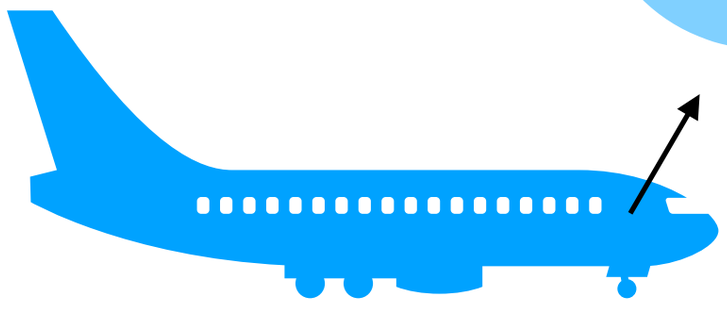


Pilot Flying

Pilot Monitoring

Time:

t_2



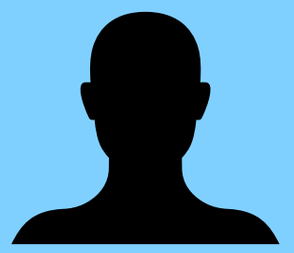
Pitch is too high!

Need to aim plane down!

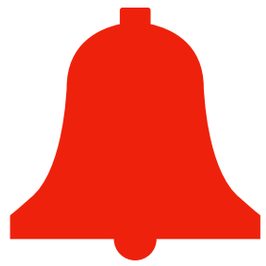
Backup Instruments

Autopilot is OFF

Pilot Flying

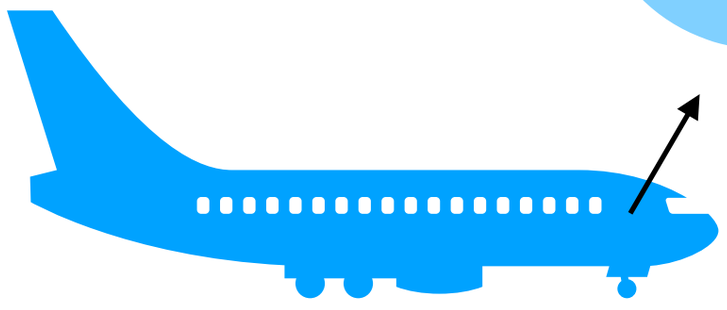


Pilot Monitoring

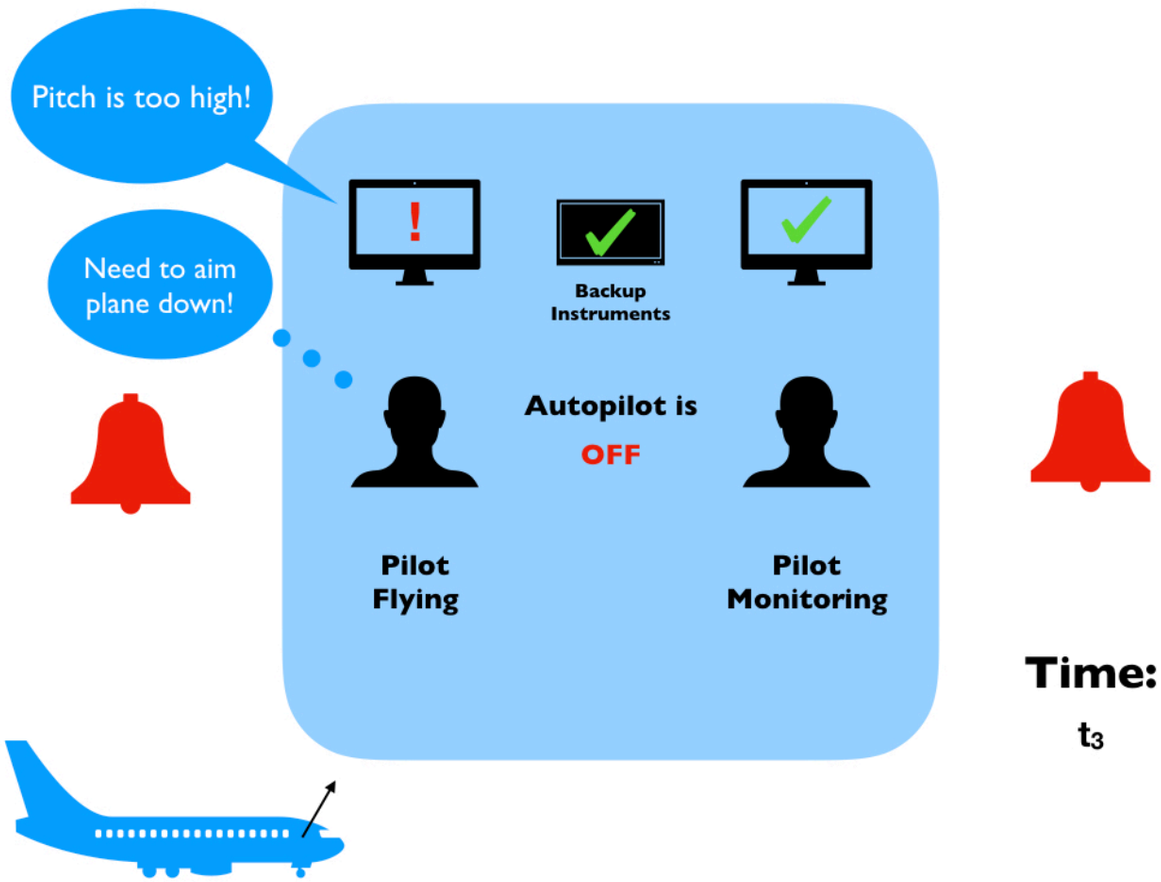


Time:

t_3



What Happened?

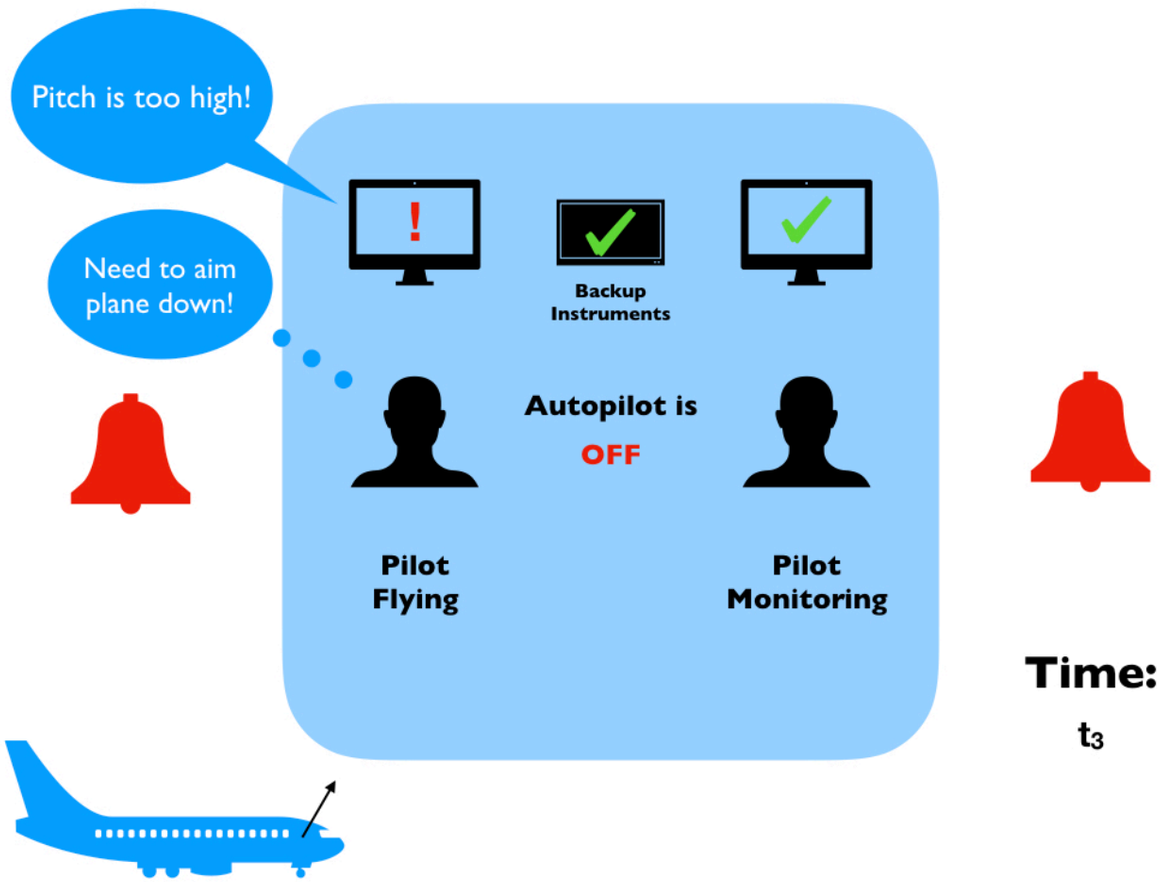


Time:

t_3

What Happened?

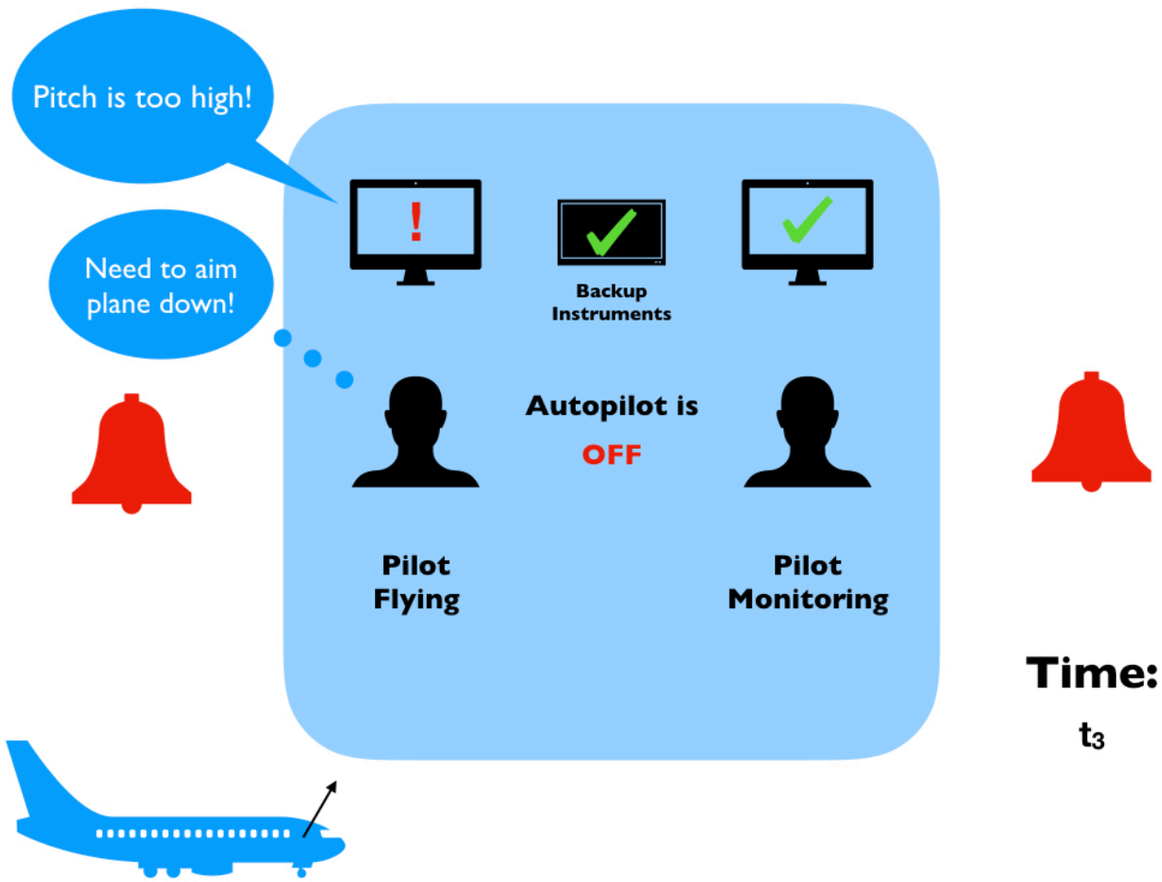
- Each pilot's display has its own set of sensors



Time:

t_3

What Happened?



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  - A faulty sensor feeding the PF's display gave an incorrect reading

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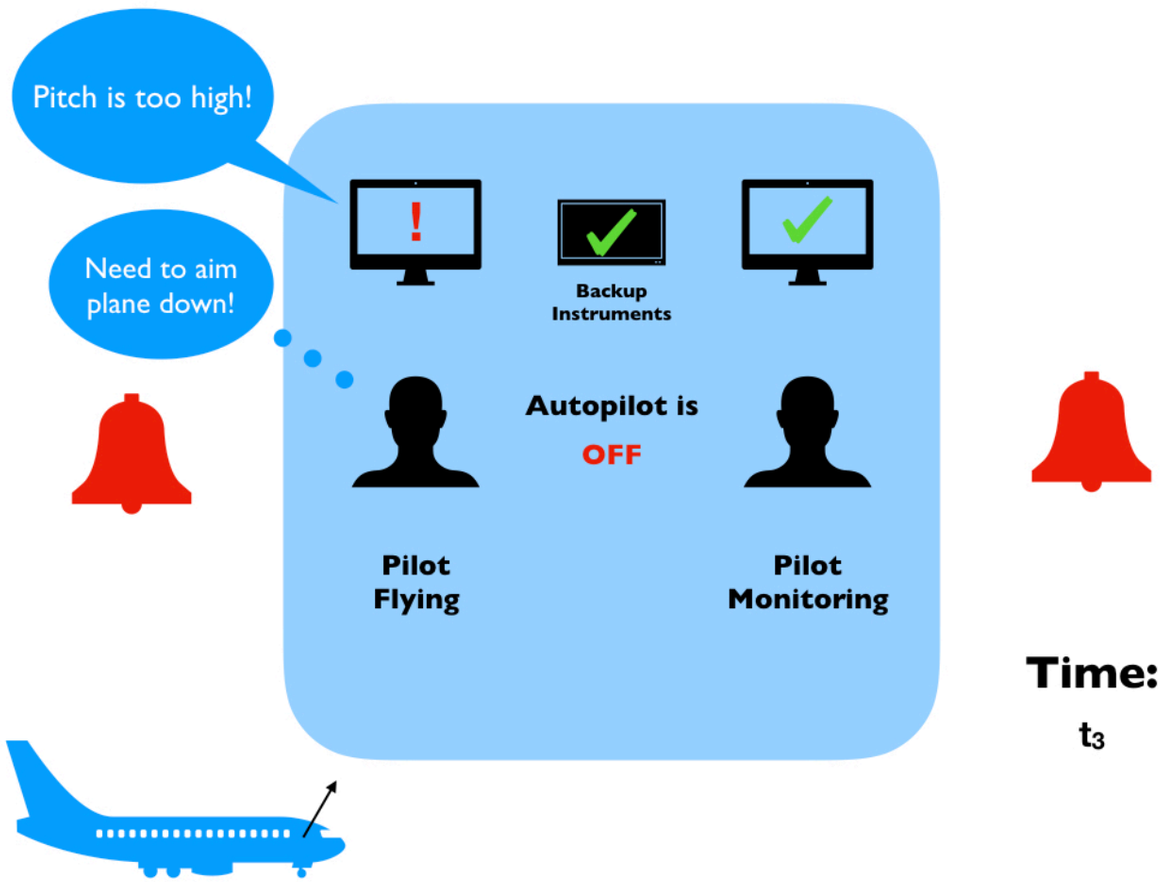

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- Typically, a Comparator Function continuously monitors sensor readings

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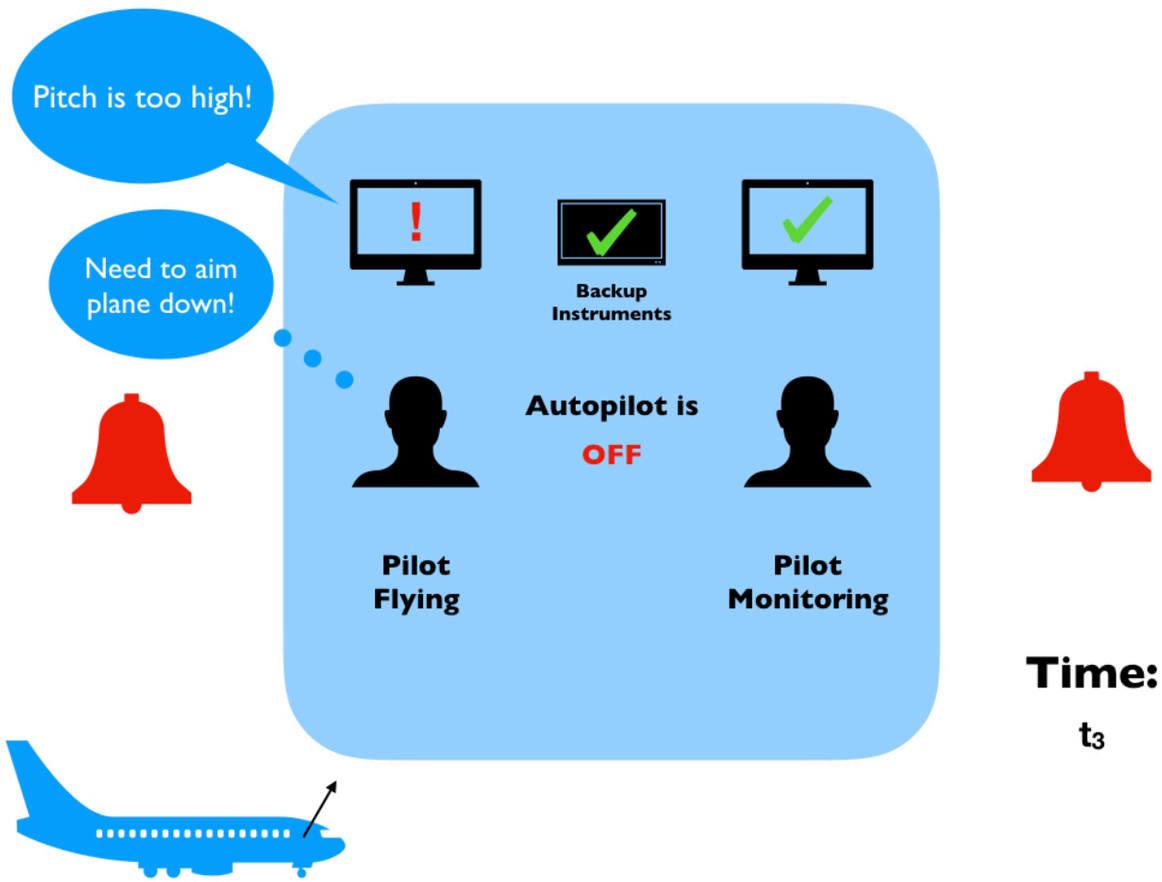

- Each pilot's display has its own set of sensors
  - A faulty sensor feeding the PF's display gave an incorrect reading
- Typically, a Comparator Function continuously monitors sensor readings
- This was disabled by a Declutter Function

How could an automated reasoner have helped?

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- Instantly detect the inconsistency

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    - In this case, notice that Pilot 1's sensor reading seems unusual, and that Pilot 2's reading matches the backup instruments.

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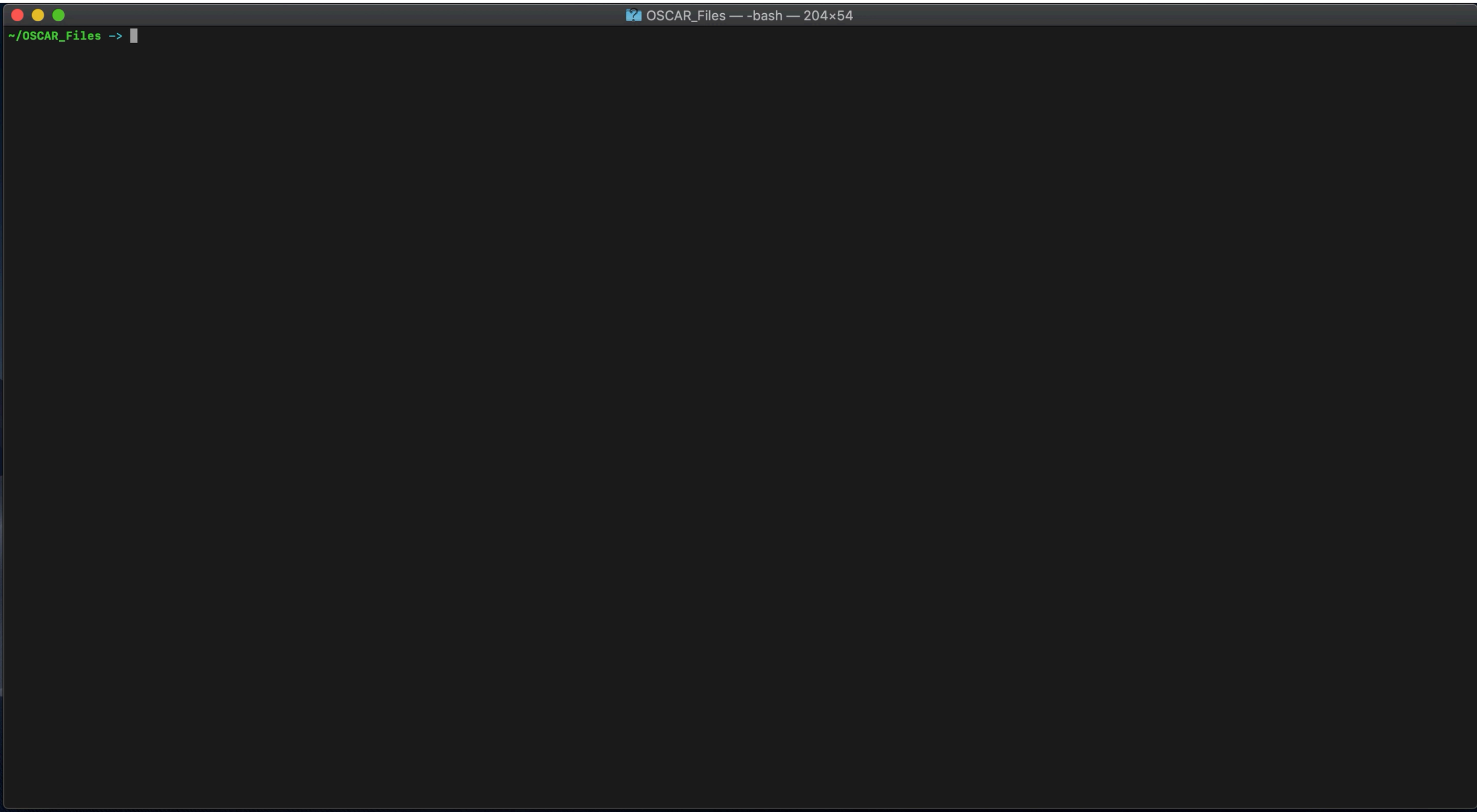
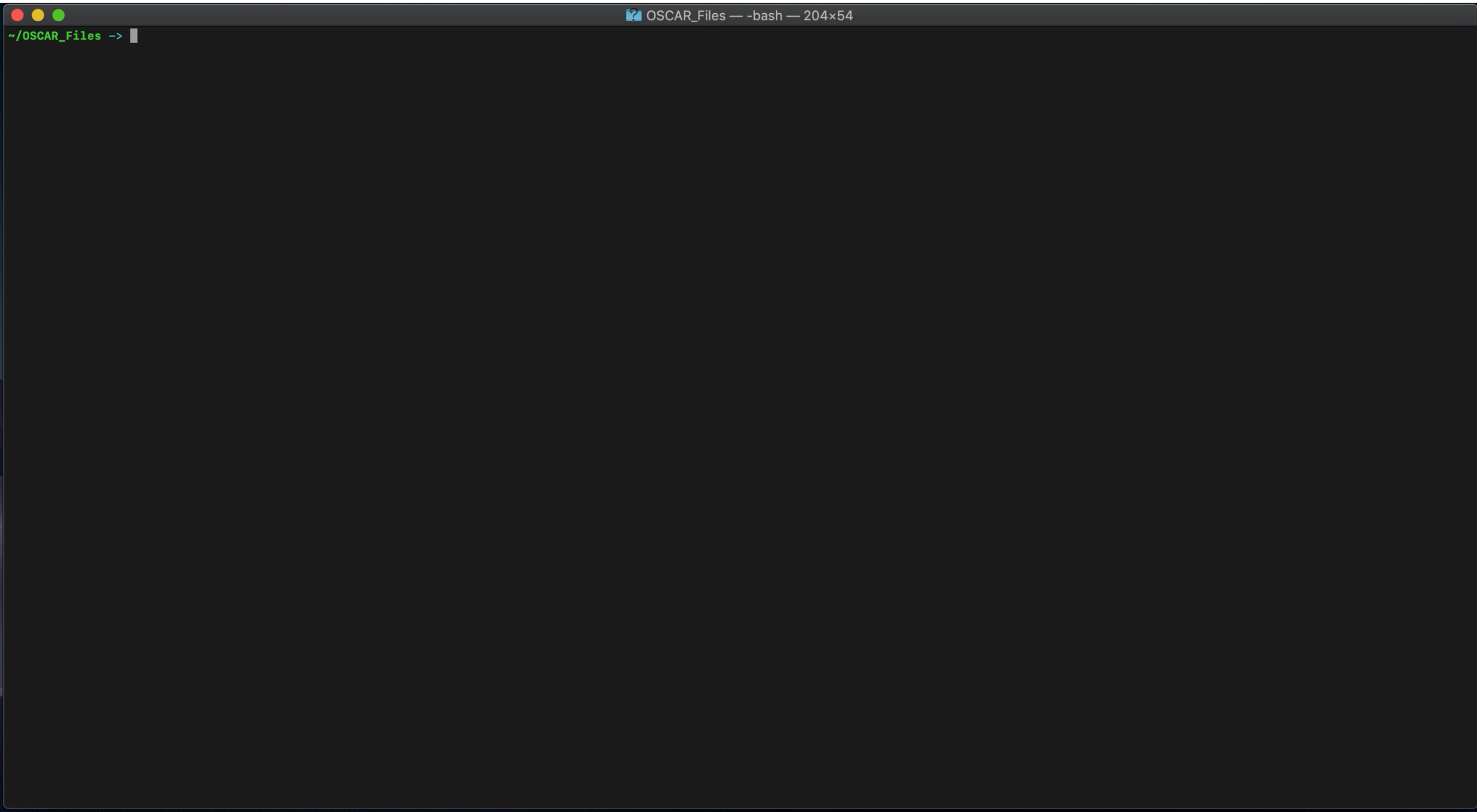
- Instantly detect the inconsistency
    - In this case, notice that Pilot 1's sensor reading seems unusual, and that Pilot 2's reading matches the backup instruments.
- Find a solution
    - In this case, send sensor readings from Pilot 2's sensors to Pilot 1's display, ignoring faulty data

A Solution in OSCAR



A Solution in OSCAR



```
Problem #1
This is a solution to the airplane crash scenario
Given premises:
     ~(ReadsNormal iru1)    justification = 1.0
     (ReadsNormal iru2)    justification = 1.0
     (MatchesBackup iru2)    justification = 1.0
     (all i1)(all i2)(((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude)    justification = 0.9
Ultimate epistemic interests:
     NormalAttitude    interest = 0.9

    FORWARDS PRIMA FACIE REASONS
      PF-REASON_1.1:   {~(ReadsNormal iru1)} ||=> ~NormalAttitude   strength = 0.6

 ================== ULTIMATE EPISTEMIC INTERESTS ==================
   Interest in NormalAttitude
   is answered affirmatively by node 14
 --------------------------------------------------

 Elapsed time = 0.022 sec

 ================================================================================
 ARGUMENT #1
 This is an undefeated argument of strength 0.9 for:
       NORMALATTITUDE
  which is of ultimate interest.

 3.  (MatchesBackup iru2)     GIVEN
 1.  ~(ReadsNormal iru1)     GIVEN
 4.  (all i1)(all i2)(((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude)     GIVEN
 7.  (all i2)(((~(ReadsNormal x0) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude)     UI from { 4 }
 8.  (((~(ReadsNormal x0) & (ReadsNormal x1)) & (MatchesBackup x1)) -> NormalAttitude)     UI from { 7 }
 9.  ((~(ReadsNormal x0) & (ReadsNormal x1)) -> ((MatchesBackup x1) -> NormalAttitude))     exportation from { 8 }
 11.  (~(ReadsNormal x0) -> ((ReadsNormal x1) -> ((MatchesBackup x1) -> NormalAttitude)))     exportation from { 9 }
 12.  ((ReadsNormal x1) -> ((MatchesBackup x1) -> NormalAttitude))     modus-ponens1 from { 11 , 1 }
 2.  (ReadsNormal iru2)     GIVEN
 13.  ((MatchesBackup iru2) -> NormalAttitude)     modus-ponens1 from { 12 , 2 }
 14.  NormalAttitude     modus-ponens1 from { 13 , 3 }

 Argument #2 support defeaters for this argument.

 This argument supports defeaters for { link 5 for node 6 } thereby providing defeaters for argument #2
 ================================================================================
 ARGUMENT #2
 This is a defeated argument for:
       (~
        (ALL I1
         (ALL I2
          (-> (& (& (~ (READSNORMAL I1)) (READSNORMAL I2)) (MATCHESBACKUP I2))
           NORMALATTITUDE))))

 1.  ~(ReadsNormal iru1)     GIVEN
 6.  ~NormalAttitude     PF-REASON_1.1 from { 1 }
 15.  ~(all i1)(all i2)(((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude)     INVERSION_FROM_CONTRADICTORY_NODES_14_AND_6 from { 6 }
 2.  (ReadsNormal iru2)     GIVEN
 4.  (all i1)(all i2)(((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude)     GIVEN
 7.  (all i2)(((~(ReadsNormal x0) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude)     UI from { 4 }
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 3.  (MatchesBackup iru2)     GIVEN
 14.  NormalAttitude     modus-ponens1 from { 13 , 3 }

 Arguments #1, #2 support defeaters for this argument.

 This argument supports defeaters for { link 4 for node 4 } thereby providing defeaters for arguments #1, #2
 ================================================================================
```
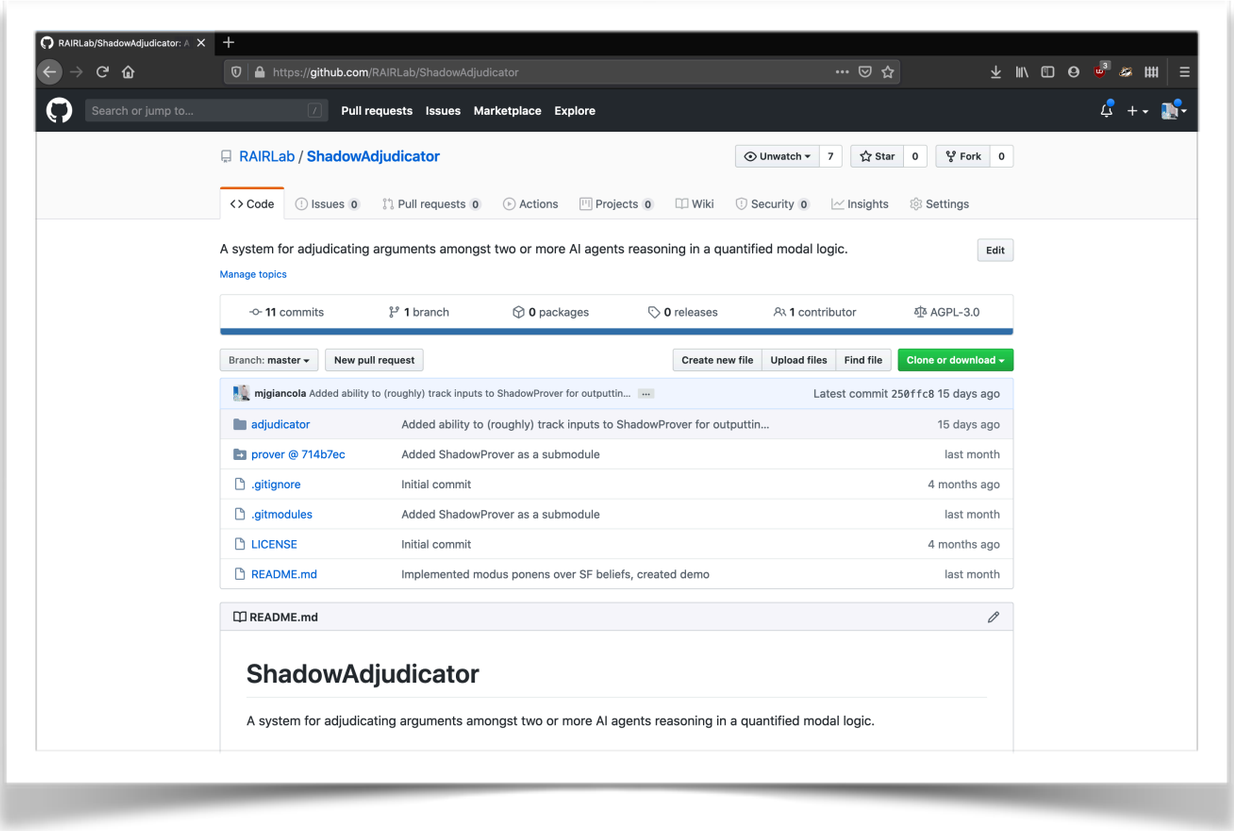

ShadowAdjudicator

ShadowAdjudicator

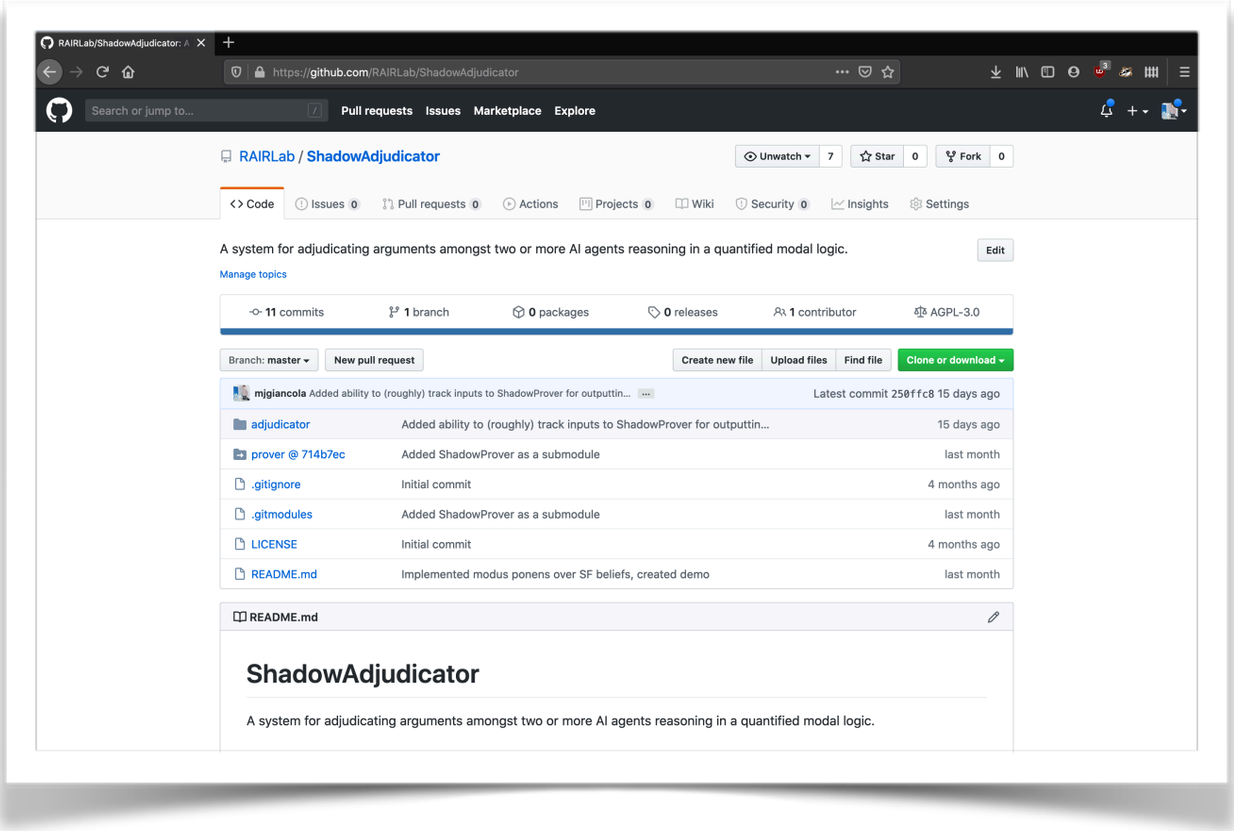
- A nascent automated reasoner for generating and adjudicating arguments



https://github.com/RAIRLab/ShadowAdjudicator

ShadowAdjudicator

- A nascent automated reasoner for generating and adjudicating arguments
- Builds upon ShadowProver



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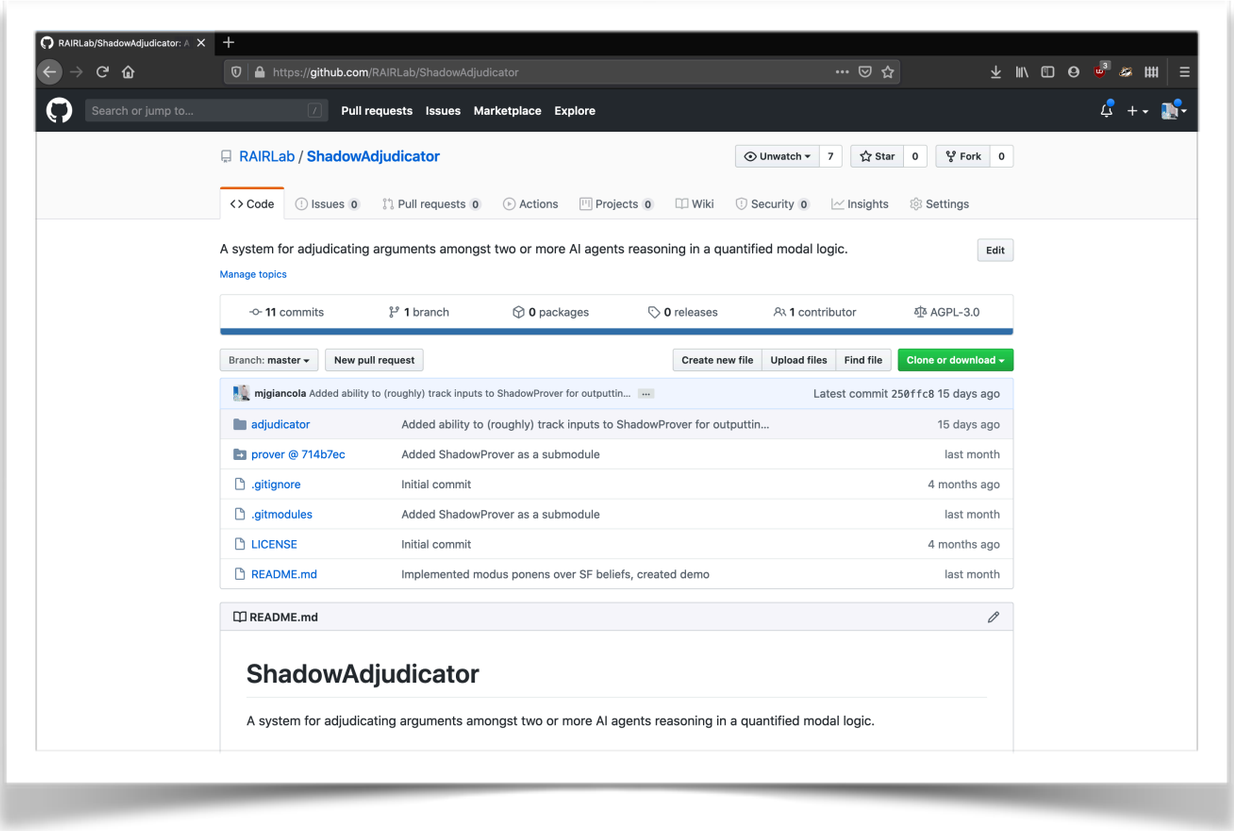
- Builds upon ShadowProver
- Uses ShadowProver for sub-proofs of modal/FOL/PL formulae



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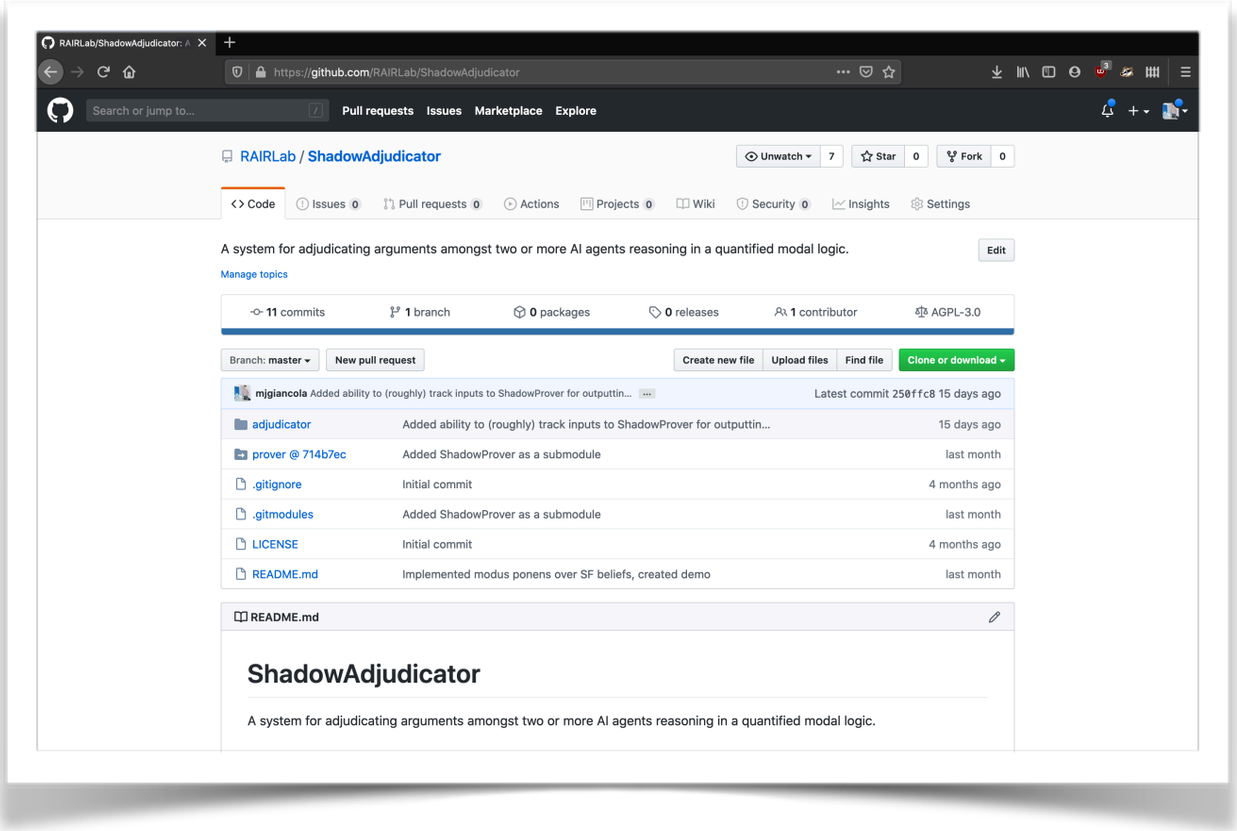
ShadowAdjudicator

- A nascent automated reasoner for generating and adjudicating arguments
- Builds upon ShadowProver
- Uses ShadowProver for sub-proofs of modal/FOL/PL formulae
- Implements an algorithm and inference schemata for generating arguments with strength factors



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- https://rair.cogsci.rpi.edu/projects/automated-reasoners/oscar/
  - Software to run OSCAR
  - For files to run example from today, email me: mike.j.giancola@gmail.com.

- Licato, John. "Formalizing deceptive reasoning in breaking bad: Default reasoning in a doxastic logic." *2015 AAAI Fall Symposium Series*. 2015.
  - https://www.aaai.org/ocs/index.php/FSS/FSS15/paper/download/11669/11486