

The Dangers of Inconsistency

Selmer Bringsjord
Mike Giancola



Are Humans Rational?
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Sponsored by



Motivation

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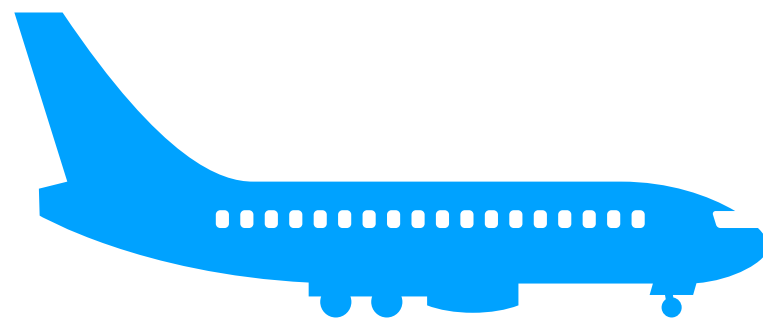
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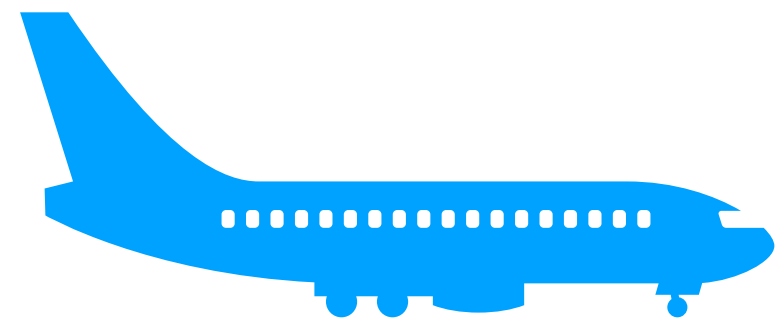
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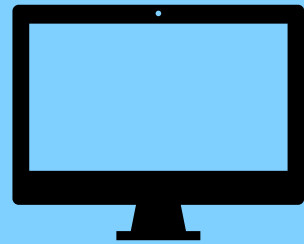
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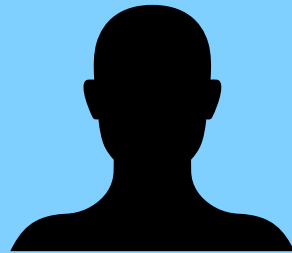
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- Underlying logic could be inconsistent 
- Inconsistency could be inherent to the domain
 - e.g. Belief Revision
- **Goal:** Build a system which can detect inconsistencies and construct solutions





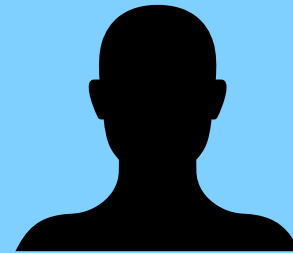


**Backup
Instruments**

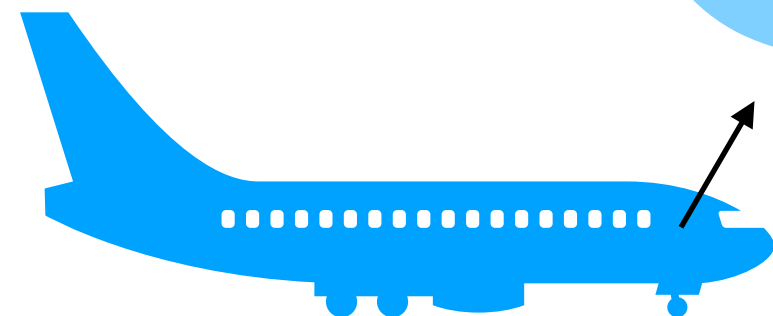


**Pilot
Flying**

**Autopilot is
ON**

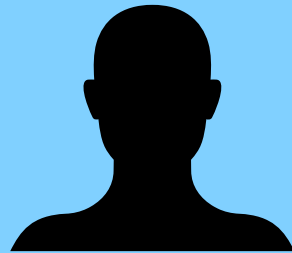


**Pilot
Monitoring**



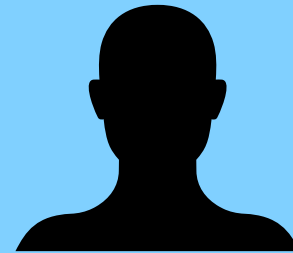


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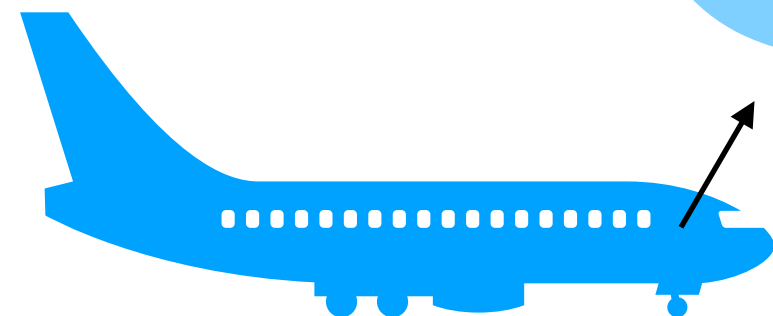
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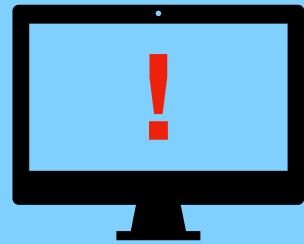


**Pilot
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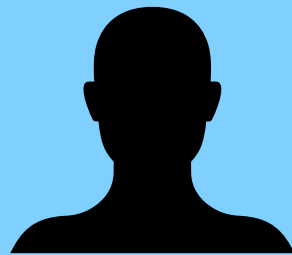
Time:
 t_0



Pitch is too high!

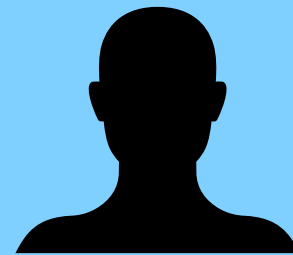


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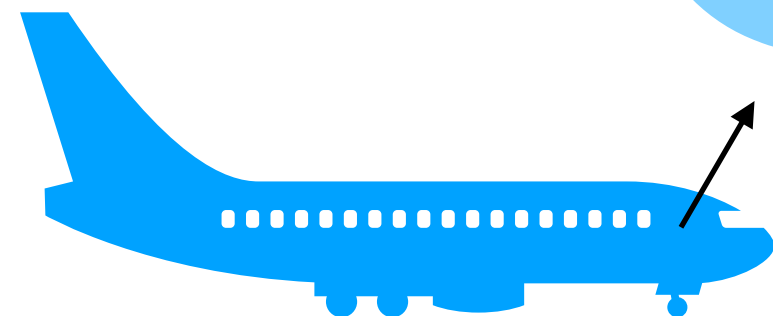
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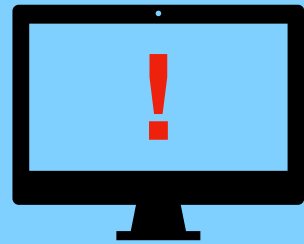
**Pilot
Monitoring**

Time:

t₁



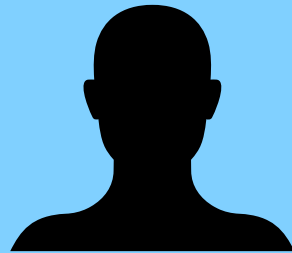
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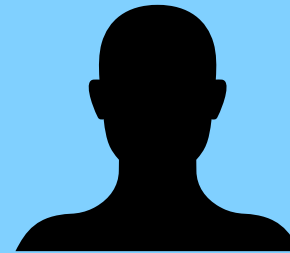
**Backup
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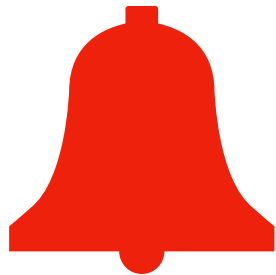
**Autopilot is
OFF**



**Pilot
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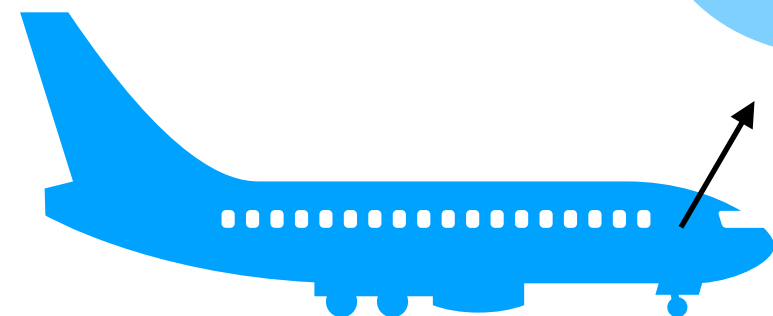


**Pilot
Monitoring**



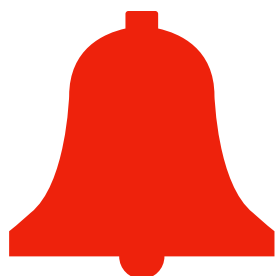
Time:

t₂

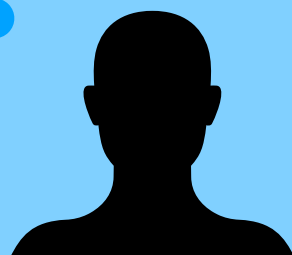


Pitch is too high!

Need to aim
plane down!



**Backup
Instruments**

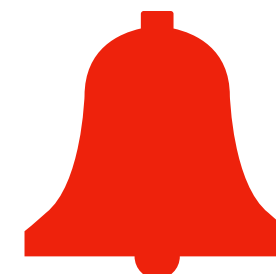


**Pilot
Flying**

**Autopilot is
OFF**

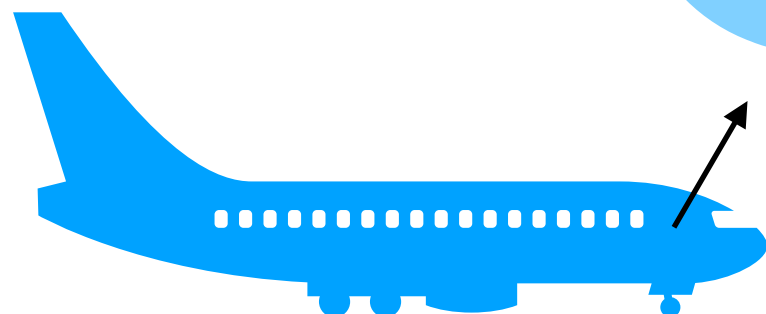


**Pilot
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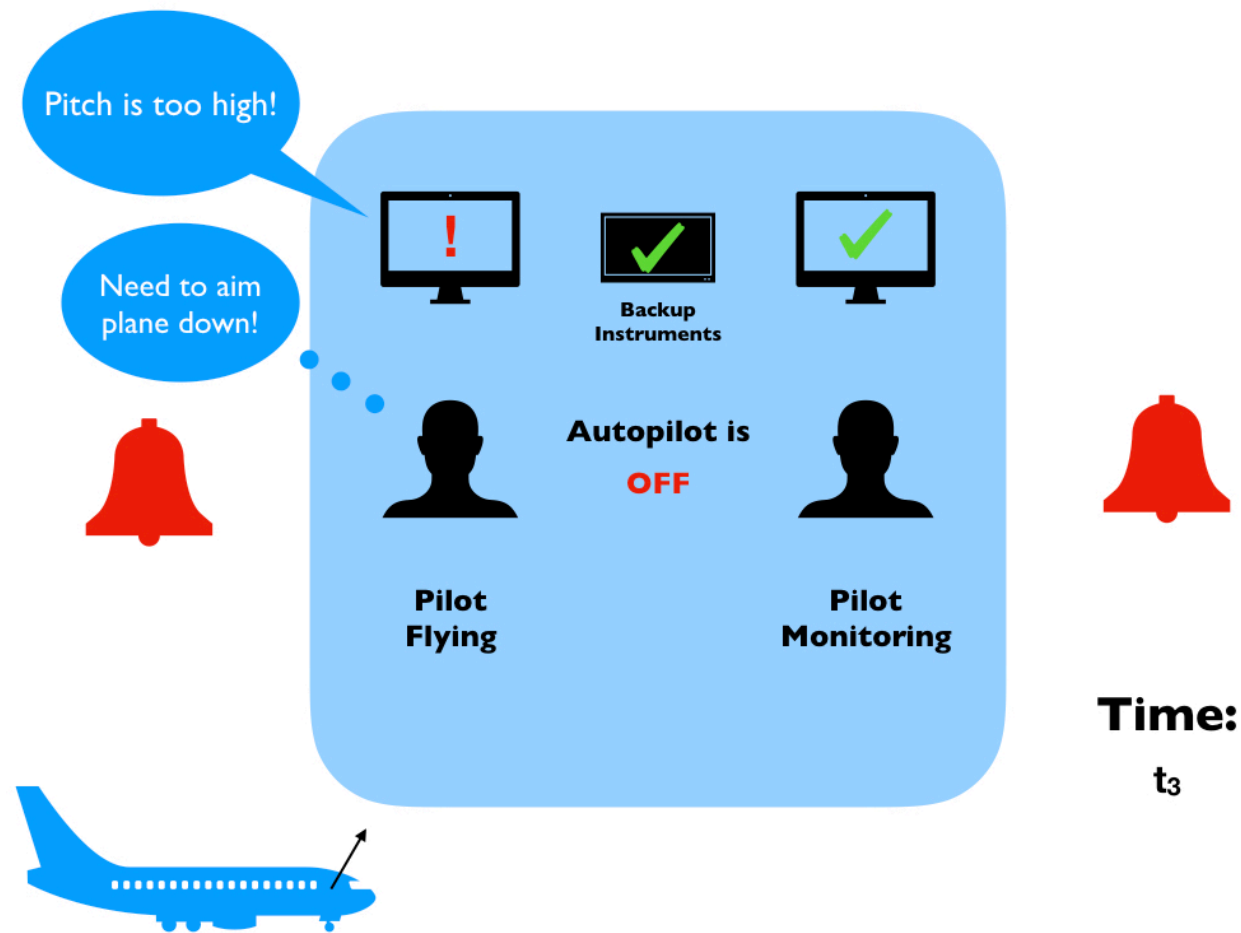


Time:

t₃

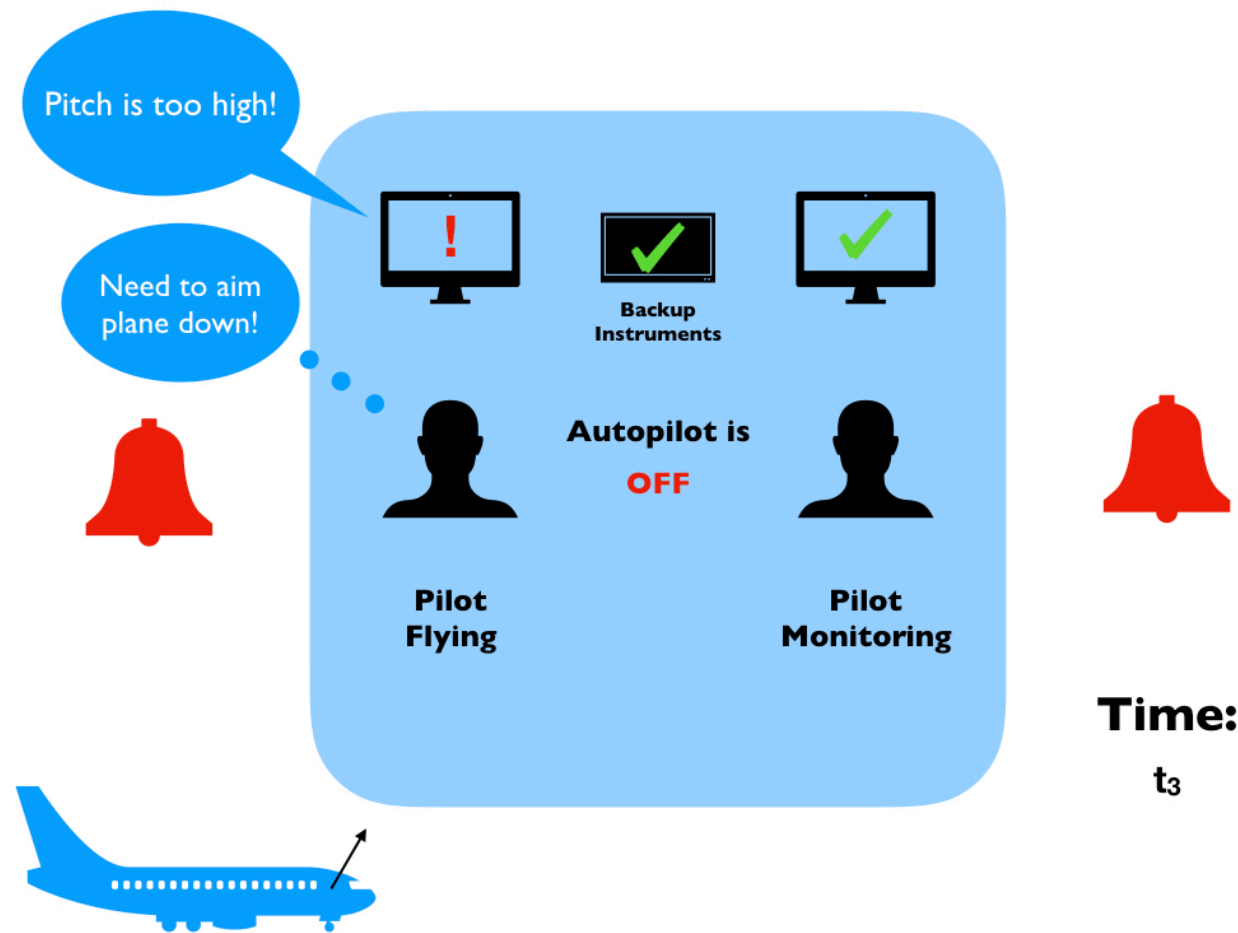


What Happened?



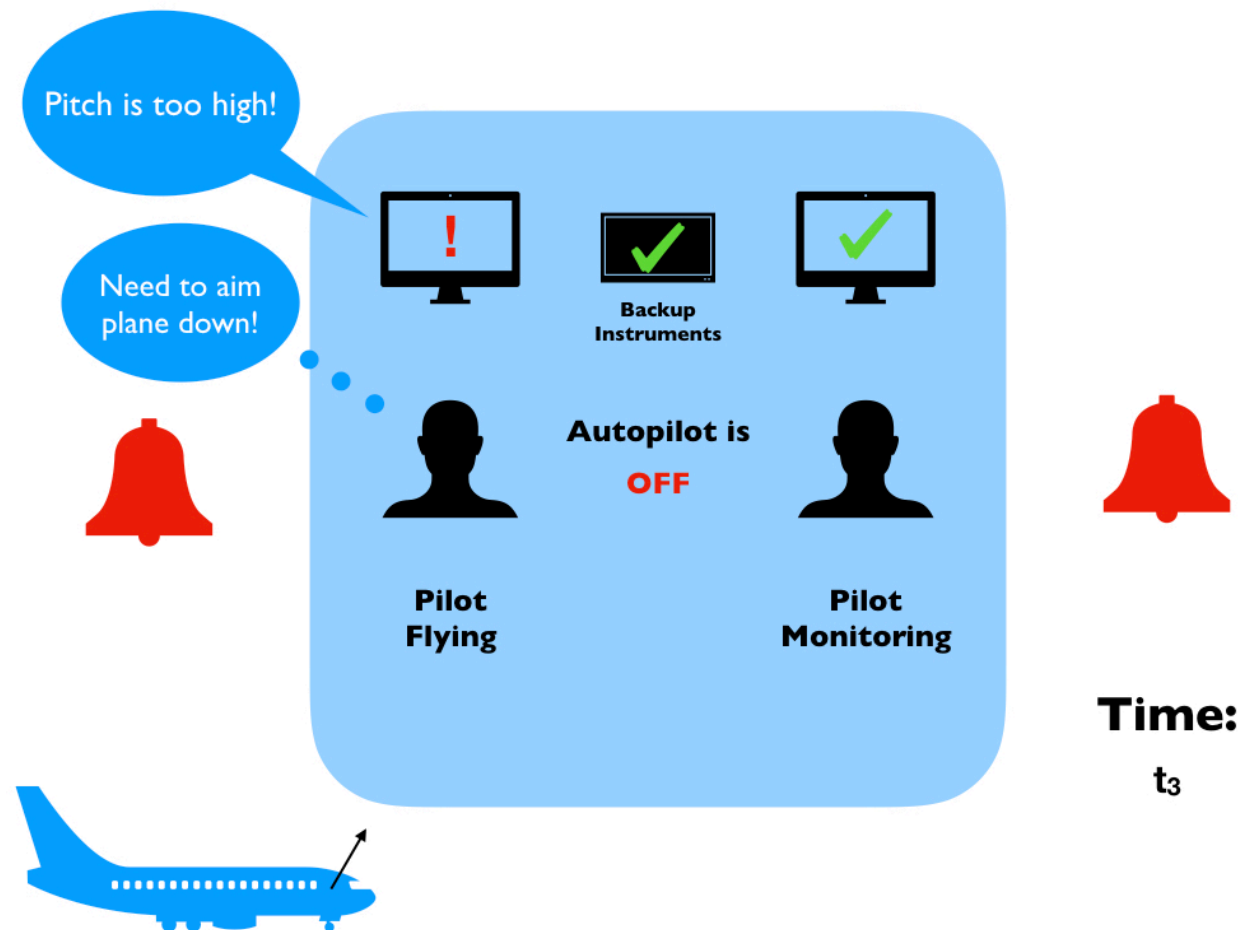
What Happened?

- Each pilot's display has its own set of sensors



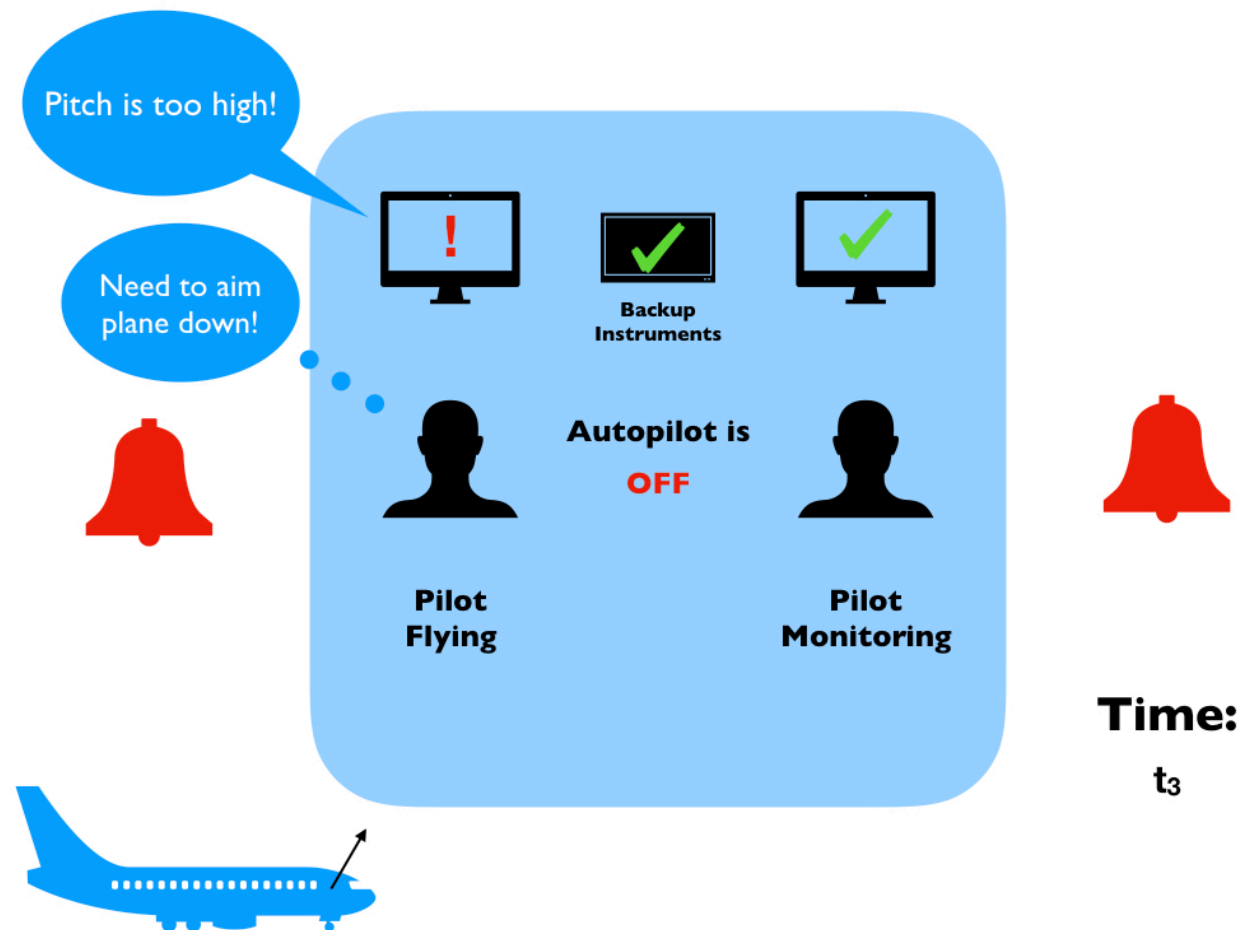
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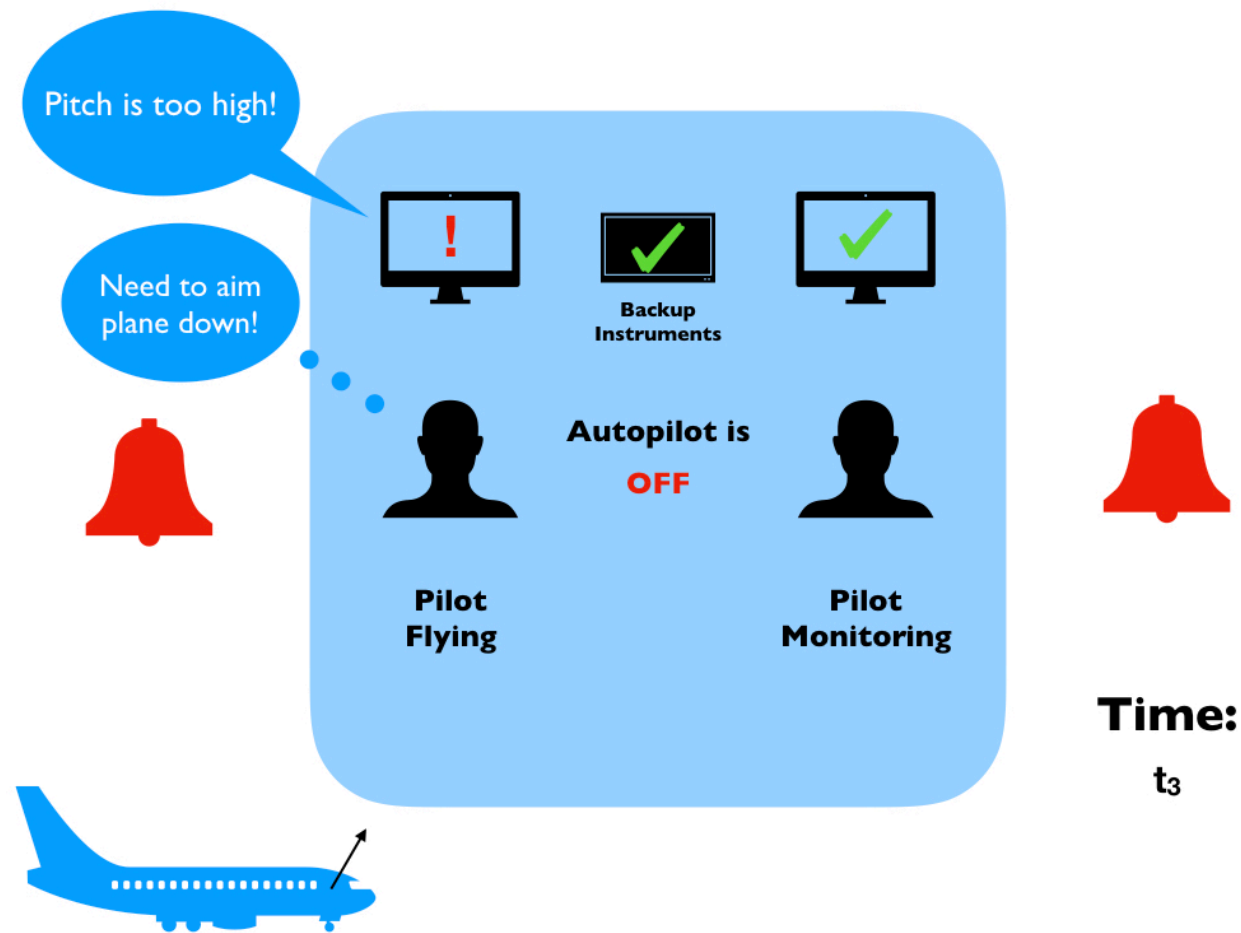


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- A faulty sensor feeding the PF's display gave an incorrect reading
- Typically, a Comparator Function continuously monitors sensor readings
- This was disabled by a Declutter Function

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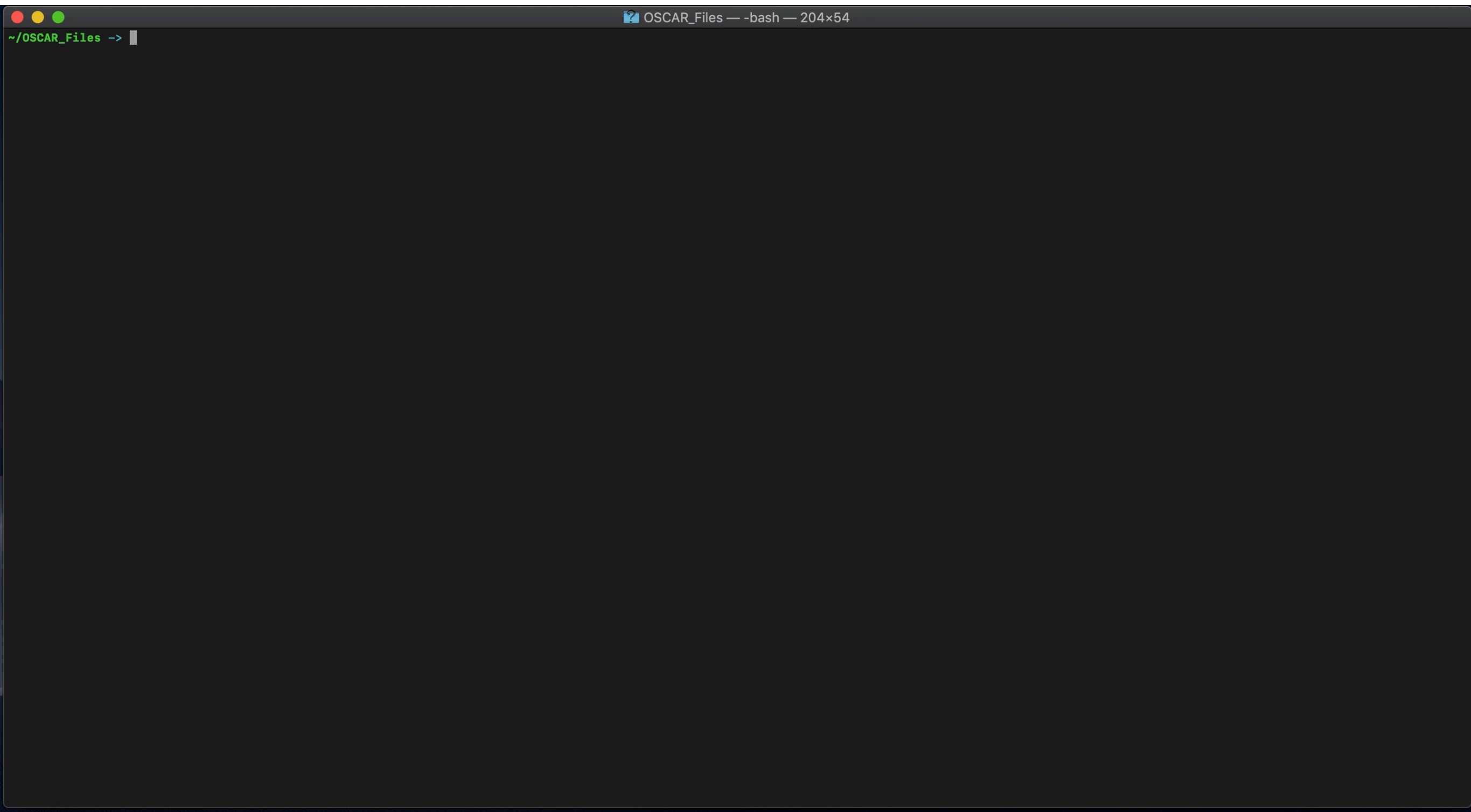
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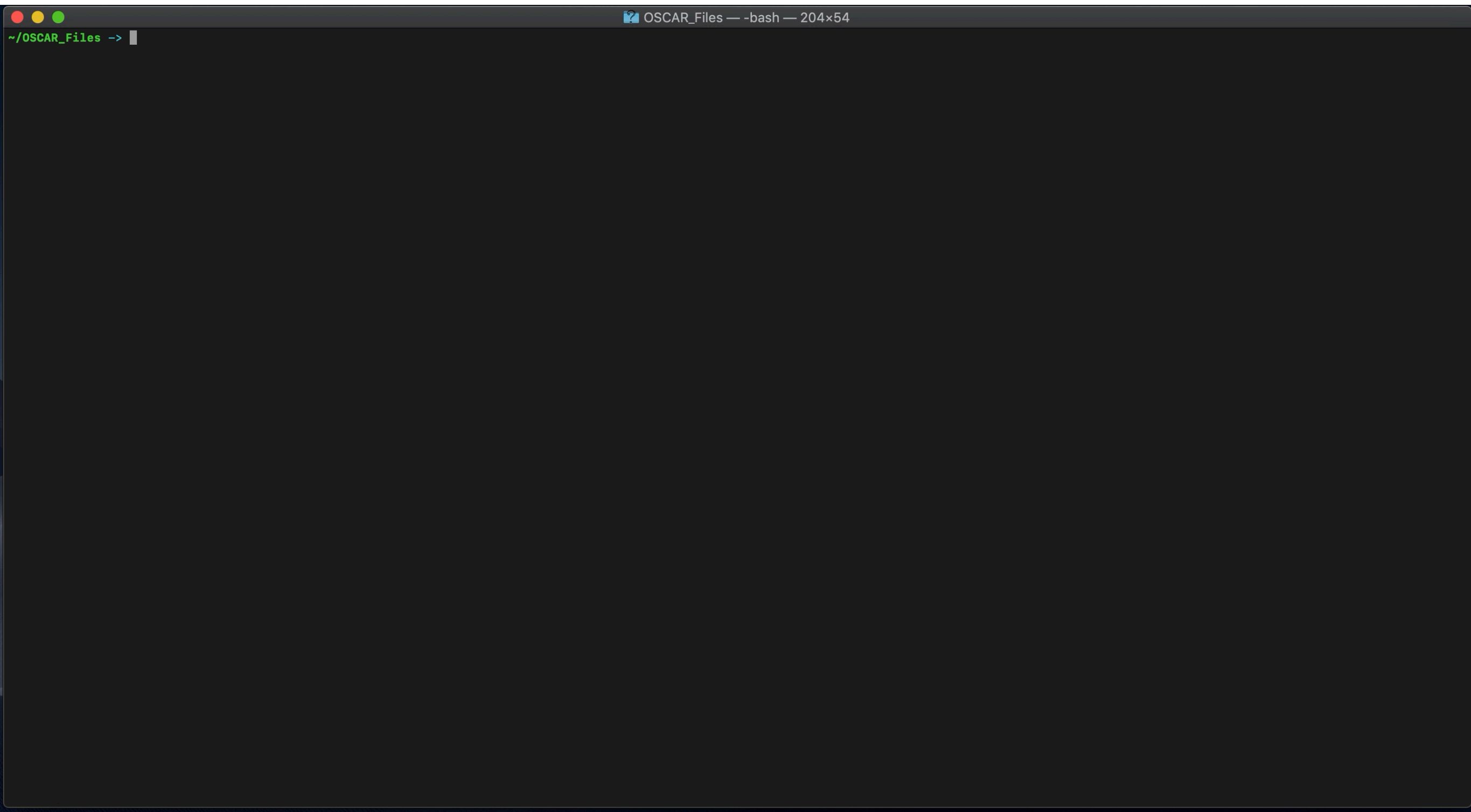
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- Find a solution
 - In this case, send sensor readings from Pilot 2's sensors to Pilot 1's display, ignoring faulty data

A Solution in OSCAR



A Solution in OSCAR



Problem #1

This is a solution to the airplane crash scenario

Given premises:

```
~(ReadsNormal iru1)      justification = 1.0
(ReadsNormal iru2)      justification = 1.0
(MatchesBackup iru2)     justification = 1.0
(all i1)(all i2)((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude      justification = 0.9
```

Ultimate epistemic interests:

```
NormalAttitude      interest = 0.9
```

FORWARDS PRIMA FACIE REASONS

```
PF-REASON_1.1: {~(ReadsNormal iru1)} ||=> ~NormalAttitude      strength = 0.6
```

===== ULTIMATE EPISTEMIC INTERESTS =====

```
Interest in NormalAttitude
is answered affirmatively by node 14
```

Elapsed time = 0.022 sec

ARGUMENT #1

This is an undefeated argument of strength 0.9 for:

```
NORMALATTITUDE
which is of ultimate interest.
```

```
3. (MatchesBackup iru2)      GIVEN
1. ~(ReadsNormal iru1)      GIVEN
4. (all i1)(all i2)((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude      GIVEN
7. (all i2)((~(ReadsNormal x0) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude      UI from { 4 }
8. (((~(ReadsNormal x0) & (ReadsNormal x1)) & (MatchesBackup x1)) -> NormalAttitude)      UI from { 7 }
9. ((~(ReadsNormal x0) & (ReadsNormal x1)) -> ((MatchesBackup x1) -> NormalAttitude))      exportation from { 8 }
11. (~(ReadsNormal x0) -> ((ReadsNormal x1) -> ((MatchesBackup x1) -> NormalAttitude)))      exportation from { 9 }
12. ((ReadsNormal x1) -> ((MatchesBackup x1) -> NormalAttitude))      modus-ponens1 from { 11 , 1 }
2. (ReadsNormal iru2)      GIVEN
13. ((MatchesBackup iru2) -> NormalAttitude)      modus-ponens1 from { 12 , 2 }
14. NormalAttitude      modus-ponens1 from { 13 , 3 }
```

Argument #2 support defeaters for this argument.

This argument supports defeaters for { link 5 for node 6 } thereby providing defeaters for argument #2

ARGUMENT #2

This is a defeated argument for:

```
(~
  (ALL I1
    (ALL I2
      (-> (& (& (~ (READSNORMAL I1)) (READSNORMAL I2)) (MATCHESBACKUP I2))
        NORMALATTITUDE))))
```

```
1. ~(ReadsNormal iru1)      GIVEN
6. ~NormalAttitude      PF-REASON_1.1 from { 1 }
15. ~(all i1)(all i2)((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude      INVERSION_FROM_CONTRADICTIONARY_NODES_14_AND_6 from { 6 }
2. (ReadsNormal iru2)      GIVEN
4. (all i1)(all i2)((~(ReadsNormal i1) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude      GIVEN
7. (all i2)((~(ReadsNormal x0) & (ReadsNormal i2)) & (MatchesBackup i2)) -> NormalAttitude      UI from { 4 }
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13. ((MatchesBackup iru2) -> NormalAttitude)      modus-ponens1 from { 12 , 2 }
3. (MatchesBackup iru2)      GIVEN
14. NormalAttitude      modus-ponens1 from { 13 , 3 }
```

Arguments #1, #2 support defeaters for this argument.

This argument supports defeaters for { link 4 for node 4 } thereby providing defeaters for arguments #1, #2

For More...

- <https://rair.cogsci.rpi.edu/projects/automated-reasoners/oscar/>
- Software to run OSCAR
- For files to run example from today, email me:
mike.j.giancola@gmail.com.
- Licato, John. "Formalizing deceptive reasoning in breaking bad: Default reasoning in a doxastic logic." *2015 AAI Fall Symposium Series*. 2015.
- <https://www.aaai.org/ocs/index.php/FSS/FSS15/paper/download/11669/11486>